

# Generalized Probabilistic Modus Ponens <sup>1</sup>

*Giuseppe Sanfilippo*<sup>a</sup> Niki Pfeifer <sup>b</sup> Angelo Gilio<sup>c</sup>

<sup>a</sup>(*Speaker*) Department of Mathematics and Computer Science, University of Palermo, Italy  
giuseppe.sanfilippo@unipa.it

<sup>b</sup>Munich Center for Mathematical Philosophy (LMU Munich), Germany  
Niki.Pfeifer@lrz.uni-muenchen.de

<sup>c</sup>Department SBAI, University of Rome "La Sapienza", Italy  
angelo.gilio@sbai.uniroma1.it

Lugano, July 13, 2017

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<sup>1</sup>Full paper available at  
[http://dx.doi.org/10.1007/978-3-319-61581-3\\_43](http://dx.doi.org/10.1007/978-3-319-61581-3_43)

# Abstract

- ▶ Modus ponens (*from  $A$  and “if  $A$  then  $C$ ” infer  $C$* ) is one of the most basic inference rules.
- ▶ The probabilistic modus ponens allows for managing uncertainty by transmitting assigned uncertainties from the premises to the conclusion (i.e., *from  $P(A)$  and  $P(C|A)$  infer  $P(C)$* ).
- ▶ We generalize the probabilistic modus ponens by replacing  $A$  by the conditional event  $A|H$ .
- ▶ The resulting inference rule involves iterated conditionals (formalized by conditional random quantities) and propagates previsions from the premises to the conclusion.
- ▶ Interestingly, the propagation rules for the lower and the upper bounds on the conclusion of the generalized probabilistic modus ponens coincide with the respective bounds on the conclusion of the (non-nested) probabilistic modus ponens.

# Modus ponens

Modus ponens	Instantiation
$A$	The son gets a B
If $A$ , then $C$	If the son gets a B, then the mother is angry
$C$	The mother is angry

# Probabilistic MP

We recall that, given two logically independent events  $A$  and  $C$ , the set of all coherent assessment  $(x, y)$  on  $\{A, C|A\}$  is the unit square  $[0, 1]^2$ .

	Modus Ponens	Probabilistic Modus Ponens
(Categorical prem.)	$A$	$P(A) = x$
(Conditional prem.)	If $A$ , then $C$	$P(C A) = y$
(Conclusion)	$C$	$xy \leq P(C) \leq xy + 1 - x$

That is, the set of all coherent assessment  $(x, y, z)$  on  $\{A, C|A, C\}$  is

$$\{(x, y, z) \in [0, 1]^3 : (x, y) \in [0, 1]^2, xy \leq z \leq xy + 1 - x\}$$



# Generalized Probabilistic MP

We will generalize the probabilistic modus ponens by replacing the categorical premise (i.e.,  $A$ ) and the antecedent of the conditional premise (i.e.,  $A$  in “if  $A$  then  $C$ ”) by the conditional event  $A|H$ .

Generalized Modus Ponens	Generalized Probabilistic Modus Ponens
$A H$	$P(A H) = x$
If $A H$ , then $C$	$\mathbb{P}(C (A H)) = y$ (What is $C (A H)$ ?)
$C$	$P(C) \in [?, ?]$

What does the conditional premise (i.e., an **iterated conditional**) mean and how can we assess its uncertainty?

What is the set of all coherent assessment  $(x, y)$  on  $\{A|H, C|(A|H)\}$  ?

What is the set of all coherent assessment  $(x, y, z)$  on  $\{A|H, C|(A|H), C\}$  ?

## Cond. probabilities as probabilities of conditional event

By using the same symbols to denote events and their indicators, agreeing to the betting metaphor of the coherence framework, if you assess  $p = P(A|H)$ , then coherence requires that  $p = \mathbb{P}(AH + p\bar{H})$ . Thus, we identify the conditional event  $A|H$  as the following random quantity

(see, e.g., Lad, 1996; Gilio & Sanfilippo, 2014)

$$A|H = AH + p\bar{H} = \begin{cases} 1, & \text{if } AH \text{ is true,} \\ 0, & \text{if } \bar{A}H \text{ is true,} \\ p, & \text{if } \bar{H} \text{ is true,} \end{cases}$$

Given a random quantity  $X$  and an event  $H$ , we identify

$$X|H = XH + \mu\bar{H}, \text{ where } \mu = \mathbb{P}(X|H).$$

# Conjoined conditionals

## Definition (Conjunction)

Given any pair of conditional events  $A|H$  and  $B|K$ , with  $P(A|H) = x$ ,  $P(B|K) = y$ , we define their *conjunction* as the following conditional random quantity (see, e.g., Gilio & Sanfilippo, 2013a, 2013b, 2014)

$$(A|H) \wedge (B|K) = \min \{A|H, B|K\} | (H \vee K) = \min \{AH + x\bar{H}, BK + y\bar{K}\} | (H \vee K).$$

Of course  $(A|H) \wedge (B|H) = (A \wedge B)|H$ .

Notice that, if  $x = y = 1$ , then the conditional events  $A|H = AH + x\bar{H}$ ,  $B|K = BK + y\bar{K}$  coincide with the material conditionals  $AH + \bar{H}$ ,  $BK + \bar{K}$  and we recover the quasi conjunction of Adams:

$$\min \{AH + \bar{H}, BK + \bar{K}\} | (H \vee K) = \text{QC}(A|H, B|K)$$



## Interpretation by the betting scheme

By assessing  $\mathbb{P}[(A|H) \wedge (B|K)] = z$ , you agree to pay  $z$  with the proviso that you will receive:

$$(A|H) \wedge (B|K) = \begin{cases} 1, & \text{if } AHBK \text{ is true,} \\ 0, & \text{if } \overline{A}H \text{ is true or } \overline{B}K \text{ is true,} \\ x = P(A|H), & \text{if } \overline{H}BK \text{ is true,} \\ y = P(B|K), & \text{if } \overline{K}AH \text{ is true,} \\ z = \mathbb{P}[(A|H) \wedge (B|K)], & \text{if } \overline{H}\overline{K} \text{ is true.} \end{cases}$$

In other words, you will receive:

- ▶ 1, if both conditional events are true;
- ▶ 0, if at least one of the conditional events is false;
- ▶ the probability of that conditional event which is void, if a conditional event is void and the other one is true;
- ▶ the quantity that you paid, if both conditional events are void.

Fréchet-Hoeffding bounds (Gilio & Sanfilippo, 2014):  $z$  is coherent iff:

$$\max\{x + y - 1, 0\} \leq z \leq \min\{x, y\}. \quad (1)$$

## Quasi-Conjunction and Conjunction

Let  $A, H, B, K$  be log. ind. events, with  $H \neq \perp, K \neq \perp$ . Assuming that  $x = P(A|H)$  and  $y = P(B|K)$ , we obtain

	$A H$	$B K$	$QC(A H, B K)$	$A H \wedge B K$
$C_1 = AHBK$	$\Rightarrow$ 1	1	1	1
$C_2 = AHB^cK$	$\Rightarrow$ 1	0	0	0
$C_3 = A^cHBK$	$\Rightarrow$ 0	1	0	0
$C_4 = A^cHB^cK$	$\Rightarrow$ 0	0	0	0
$C_5 = H^cBK$	$\Rightarrow$ $x$	1	1	$x$
$C_6 = AHK^c$	$\Rightarrow$ 1	$y$	1	$y$
$C_7 = A^cHK^c$	$\Rightarrow$ 0	$y$	0	0
$C_8 = H^cB^cK$	$\Rightarrow$ $x$	0	0	0
$C_9 = H^cK^c$	$\Rightarrow$ $x$	$y$	$\nu = \mathbb{P}(QC(A H, B K))$	$z = \mathbb{P}(A H \wedge B K)$

QC bounds:  $\nu$  is coherent iff  $\max\{x + y - 1, 0\} \leq \nu \leq S_0^H(x, y)$

$$\text{where } S_0^H(x, y) = \begin{cases} \frac{x-y-2xy}{1-xy}, & (x, y) \neq (1, 1), \\ 1, & (x, y) = (1, 1) \end{cases}$$

# Iterated conditional and betting scheme

## Definition

The iterated conditional  $(B|K)|(A|H)$  is the conditional random quantity

$$(B|K)|(A|H) = (B|K) \wedge (A|H) + \mu \cdot \bar{A}|H, \quad (2)$$

where  $\mu = \mathbb{P}[(B|K)|(A|H)]$ . Notice that (2) is a generalization of  $A|H = A \wedge H + p \cdot \bar{H}$ , where  $p = P(A|H)$ .

In the context of betting scheme  $\mu$  represents the amount you agree to pay with the proviso that you will receive the quantity

$$(B|K)|(A|H) = \begin{cases} 1, & \text{if } AHBK \text{ true,} \\ 0, & \text{if } AH\bar{B}K \text{ true,} \\ y, & \text{if } AH\bar{K} \text{ true,} \\ \mu, & \text{if } \bar{A}H \text{ true,} \\ x + \mu(1 - x), & \text{if } \bar{H}BK \text{ true,} \\ \mu(1 - x), & \text{if } \bar{H}\bar{B}K \text{ true,} \\ z + \mu(1 - x), & \text{if } \bar{H}\bar{K} \text{ true.} \end{cases}$$

Coherence requires that  $z + \mu(1 - x) = \mu \in [0, 1]$ .

## Some properties

- ▶ The **product rule**: (Gilio & Sanfilippo, 2014)

$$\mathbb{P}[(B|K) \wedge (A|H)] = \mathbb{P}[(B|K)|(A|H)] \cdot P(A|H). \quad (3)$$

Moreover, assuming  $x = P(A|H) > 0$ , one has:

$$\mathbb{P}[(B|K)|(A|H)] = \mu = \frac{\mathbb{P}[(B|K) \wedge (A|H)]}{P(A|H)} = \frac{z}{x}.$$

- ▶ **Decomposition formula**

$$B|K = (A|H) \wedge (B|K) + (\bar{A}|H) \wedge (B|K). \quad (4)$$

By the linearity of prevision, and by the product rule, we obtain

$$P(B|K) = \mathbb{P}[(B|K)|(A|H)]P(A|H) + \mathbb{P}[(B|K)|(\bar{A}|H)]P(\bar{A}|H).$$

## A particular case

If  $K = \Omega$  (by replacing  $B$  with  $C$ ), then we obtain from the decomposition formula:

$$C = (A|H) \wedge C + (\bar{A}|H) \wedge C, \quad (5)$$

$$P(C) = \mathbb{P}[C|(A|H)]P(A|H) + \mathbb{P}[C|(\bar{A}|H)]P(\bar{A}|H) \quad (6)$$

By applying Definition 2, with  $K = \Omega$  and by replacing  $B$  with  $C$ , we obtain  $C|(A|H) = C \wedge (A|H) + \mu\bar{A}|H$ . That is,

$$C|(A|H) = \begin{cases} 1, & \text{if } AHC \text{ true,} \\ 0, & \text{if } AH\bar{C} \text{ true,} \\ \mu, & \text{if } \bar{A}H \text{ true,} \\ x + \mu(1-x), & \text{if } \bar{H}C \text{ true,} \\ \mu(1-x), & \text{if } \bar{H}\bar{C} \text{ true,} \end{cases}$$

Notice that  $C|(A|H) \neq C|AH$ .

# Coherent sets and coherent extensions

## ▶ Theorem (2)

Let three logically independent events  $A, C, H$  be given, with  $A \neq \perp$ ,  $H \neq \perp$ . The set of all coherent assessments  $\mathcal{M} = (x, y, z)$  on  $\mathcal{F} = \{A|H, C|(A|H), C|(\bar{A}|H)\}$  is the unit cube  $[0, 1]^3$ .

That is, assuming logical independence, every point  $(x, y, z) \in [0, 1]^3$  is a coherent assessment on  $\{A|H, C|(A|H), C|(\bar{A}|H)\}$ .

## ▶ Theorem (3)

Given any coherent assessment  $(x, y)$  on  $\{A|H, C|(A|H)\}$ , with  $A, C, H$  logically independent, but  $A \neq \perp$  and  $H \neq \perp$ , the extension  $z = P(C)$  is coherent if and only if  $z \in [z', z'']$ , where

$$z' = xy \quad \text{and} \quad z'' = xy + 1 - x. \quad (7)$$

That is, we generalized the probabilistic *modus ponens* to the case where the first premise  $A$  is replaced by the conditional event  $A|H$ .

# Proof

From  $P(A|H) = x$  and  $\mathbb{P}[C|(A|H)] = y$  infer  $xy \leq P(C) \leq xy + 1 - x$   
From (6), by the linearity of prevision, and the product rule, we obtain

$$z = P(C) = \underbrace{P(A|H)}_x \underbrace{\mathbb{P}[C|(A|H)]}_y + \underbrace{P(\bar{A}|H)}_{1-x} \underbrace{\mathbb{P}[C|(\bar{A}|H)]}_{t \in [0,1]}$$

From Theorem 3, given any coherent assessment  $(x, y)$  on  $\{A|H, C|(A|H)\}$ , the extension  $t = \mathbb{P}[C|(\bar{A}|H)]$  on  $C|(\bar{A}|H)$  is coherent for every  $t \in [0, 1]$ . As  $z = xy + (1 - x)t$ , it follows that

$$\underbrace{xy}_{\text{if } t=0} \leq P(C) \leq \underbrace{xy + (1 - x)}_{\text{if } t=1}$$

Prevision entailment:

$$P(A|H) = 1, \ \& \ \mathbb{P}[C|(A|H)] = 1 \implies P(C) = 1$$

# Conclusion

- ▶ We generalized the probabilistic modus ponens in terms of conditional random quantities in the setting of coherence.
- ▶ Specifically, we replaced the categorical premise  $A$  and the antecedent  $A$  of the conditional premise  $C|A$  by the conditional event  $A|H$ .
- ▶ We proved a generalized decomposition formula for conditional events and we gave some results.
- ▶ We propagated the previsions from the premises of the generalized probabilistic modus ponens to the conclusion.
- ▶ We have shown that the lower and the upper bounds on the conclusion of the generalized probabilistic modus ponens coincide with the respective bounds on the conclusion for the (non-nested) probabilistic modus ponens.



## Further work

- ▶ We will study other instantiations to obtain further generalizations of modus ponens, e.g., by also replacing the consequent  $C$  of the conditional premise  $C|A$  and the conclusion  $C$  by a conditional event  $C|K$ : from  $\{A|H, (C|K)|(A|H)\}$  infer  $C|K$ .
- ▶ We will focus on similar generalizations (also involving imprecision) of other argument forms like the probabilistic modus tollens.
- ▶ We will study similar generalization of inference rules in System P where a conditional will be replaced by an iterated one.

Thank you for your attention!

[Link to the full paper](#)

I would also like to thank the organizers of ECSQARU 2017, and in particular Alessandro Antonucci, for giving me this opportunity to talk by skype.

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