

Agreeing to Disagree and Dilation

Jiji Zhang ¹ Hailin Liu ² Teddy Seidenfeld ³

¹Lingnan University, Hong Kong

²Sun Yat-sen University, China

³Carnegie Mellon University, USA

ISIPTA '17

July 10, 2017, Lugano, Switzerland

Dilation is Responsible for “Agreeing to Disagree”

- Aumann (1976) showed that it is impossible for two Bayesian agents with a common precise prior to “agree to disagree”.
- With a common imprecise prior, “agreeing to disagree” is possible, but only thanks to the phenomenon of dilation.

Aumann's Agreement Theorem

- Suppose two agents have the same (precise) prior, ρ , over a measurable space (Ω, \mathcal{A}) .

Aumann's Agreement Theorem

- Suppose two agents have the same (precise) prior, ρ , over a measurable space (Ω, \mathcal{A}) .
- Agent i learns (privately) the value of a (measurable) partition of Ω , \mathcal{P}_i , and updates by Bayesian conditioning.

Aumann's Agreement Theorem

- Suppose two agents have the same (precise) prior, ρ , over a measurable space (Ω, \mathcal{A}) .
- Agent i learns (privately) the value of a (measurable) partition of Ω , \mathcal{P}_i , and updates by Bayesian conditioning.
- All these are *commonly* known: each agent knows them, knows that each knows them, knows that each knows that each knows them, ... *ad infinitum*.

Aumann's Agreement Theorem

- Suppose two agents have the same (precise) prior, ρ , over a measurable space (Ω, \mathcal{A}) .
- Agent i learns (privately) the value of a (measurable) partition of Ω , \mathcal{P}_i , and updates by Bayesian conditioning.
- All these are *commonly* known: each agent knows them, knows that each knows them, knows that each knows that each knows them, ... *ad infinitum*.
- Then, if it is common knowledge that agent 1's posterior of an event H is ρ_1 and agent 2's posterior of H is ρ_2 , then $\rho_1 = \rho_2$.

Aumman's Agreement Theorem

- Suppose two agents have the same (precise) prior, ρ , over a measurable space (Ω, \mathcal{A}) .
- Agent i learns (privately) the value of a (measurable) partition of Ω , \mathcal{P}_i , and updates by Bayesian conditioning.
- All these are *commonly* known: each agent knows them, knows that each knows them, knows that each knows that each knows them, ... *ad infinitum*.
- Then, if it is common knowledge that agent 1's posterior of an event H is ρ_1 and agent 2's posterior of H is ρ_2 , then $\rho_1 = \rho_2$.
- That is, the agents cannot agree to disagree!

Example of Agreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H = \{w_1, w_4\}.$$

Example of Agreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H = \{w_1, w_4\}.$$

- Suppose $\rho = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose w_1 is the true state, at which agent 1 learns $\{w_1, w_2\}$, and agent 2 learns $\{w_1, w_3\}$.

Example of Agreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H = \{w_1, w_4\}.$$

- Suppose $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose w_1 is the true state, at which agent 1 learns $\{w_1, w_2\}$, and agent 2 learns $\{w_1, w_3\}$.
- So, $p_1(H) = p(H|\{w_1, w_2\}) = \frac{1}{2} = p(H|\{w_1, w_3\}) = p_2(H)$.

Example of Agreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H = \{w_1, w_4\}.$$

- Suppose $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose w_1 is the true state, at which agent 1 learns $\{w_1, w_2\}$, and agent 2 learns $\{w_1, w_3\}$.
- So, $p_1(H) = p(H|\{w_1, w_2\}) = \frac{1}{2} = p(H|\{w_1, w_3\}) = p_2(H)$.
- Note that it is common knowledge that $p_1(H) = \frac{1}{2}$, for agent 2 can see (and agent 1 can see that agent 2 can see) that no matter which state is true, agent 1's posterior of H would be $\frac{1}{2}$.

Example of Agreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H = \{w_1, w_4\}.$$

- Suppose $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose w_1 is the true state, at which agent 1 learns $\{w_1, w_2\}$, and agent 2 learns $\{w_1, w_3\}$.
- So, $p_1(H) = p(H|\{w_1, w_2\}) = \frac{1}{2} = p(H|\{w_1, w_3\}) = p_2(H)$.
- Note that it is common knowledge that $p_1(H) = \frac{1}{2}$, for agent 2 can see (and agent 1 can see that agent 2 can see) that no matter which state is true, agent 1's posterior of H would be $\frac{1}{2}$.
- Similarly, it is also common knowledge that $p_2(H) = \frac{1}{2}$.

Example of Disagreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H' = \{w_4\}.$$

Example of Disagreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H' = \{w_4\}.$$

- Suppose $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose the true state is w_2 . Then, $p_1(H') = p(H'|\{w_1, w_2\}) = 0 \neq \frac{1}{2} = p(H'|\{w_2, w_4\}) = p_2(H')$.

Example of Disagreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H' = \{w_4\}.$$

- Suppose $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose the true state is w_2 . Then, $p_1(H') = p(H'|\{w_1, w_2\}) = 0 \neq \frac{1}{2} = p(H'|\{w_2, w_4\}) = p_2(H')$.
- But this is *not* agreeing to disagree, for neither agent knows the other's posterior of H' .

Example of Disagreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H' = \{w_4\}.$$

- Suppose $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose the true state is w_2 . Then, $p_1(H') = p(H'|\{w_1, w_2\}) = 0 \neq \frac{1}{2} = p(H'|\{w_2, w_4\}) = p_2(H')$.
- But this is *not* agreeing to disagree, for neither agent knows the other's posterior of H' .
- Indeed, if agent 1 makes her posterior known to agent 2, agent 2 will update his and reach an agreement with agent 1.

Example of Disagreement

	\mathcal{P}^2	
\mathcal{P}^1	w_1	w_2
	w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\{w_1, w_3\}, \{w_2, w_4\}\}; H' = \{w_4\}.$$

- Suppose $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and suppose the true state is w_2 . Then, $p_1(H') = p(H'|\{w_1, w_2\}) = 0 \neq \frac{1}{2} = p(H'|\{w_2, w_4\}) = p_2(H')$.
- But this is *not* agreeing to disagree, for neither agent knows the other's posterior of H' .
- Indeed, if agent 1 makes her posterior known to agent 2, agent 2 will update his and reach an agreement with agent 1.
- In general, if agents keep communicating credences to each other and updating accordingly, then the posteriors at the equilibrium must be equal (Geanakoplos & Polemarchakis, 1982).

- However, if the common prior is imprecise, represented by a set of distributions over \mathcal{A} , it is in general possible to agree to disagree.

Agreeing to Disagree with IP

- However, if the common prior is imprecise, represented by a set of distributions over \mathcal{A} , it is in general possible to agree to disagree.
- That is, two Bayesian agents learning different pieces of evidence can have different posterior sets that are common knowledge, or even different lower or upper posteriors that are common knowledge.

Agreeing to Disagree with IP

- However, if the common prior is imprecise, represented by a set of distributions over \mathcal{A} , it is in general possible to agree to disagree.
- That is, two Bayesian agents learning different pieces of evidence can have different posterior sets that are common knowledge, or even different lower or upper posteriors that are common knowledge.
- The possibility of agreeing to disagree on the lower or upper posterior is due *solely* to the possibility of dilation.

Example of Agreeing to Disagree

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}.$$

Example of Agreeing to Disagree

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}.$$

- Instead of a precise prior, suppose the two agents begin with a common imprecise prior, an ϵ -contaminated class:
 $\mathbf{Q} = \{0.8p + 0.2q \mid q \in \Lambda\}$, where $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and Λ is the set of all distributions over \mathcal{A} .

Example of Agreeing to Disagree

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}.$$

- Instead of a precise prior, suppose the two agents begin with a common imprecise prior, an ϵ -contaminated class:
 $\mathbf{Q} = \{0.8p + 0.2q \mid q \in \Lambda\}$, where $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and Λ is the set of all distributions over \mathcal{A} .
- Suppose the true state is w_1 , at which
 $\mathbf{Q}_1(H) = \mathbf{Q}(H|\{w_1, w_2\}) = [\frac{1}{3}, \frac{2}{3}]$, whereas $\mathbf{Q}_2(H) = \mathbf{Q}(H|\Omega) = [\frac{2}{5}, \frac{3}{5}]$.

Example of Agreeing to Disagree

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}.$$

- Instead of a precise prior, suppose the two agents begin with a common imprecise prior, an ϵ -contaminated class:
 $\mathbf{Q} = \{0.8p + 0.2q \mid q \in \Lambda\}$, where $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and Λ is the set of all distributions over \mathcal{A} .
- Suppose the true state is w_1 , at which
 $\mathbf{Q}_1(H) = \mathbf{Q}(H|\{w_1, w_2\}) = [\frac{1}{3}, \frac{2}{3}]$, whereas $\mathbf{Q}_2(H) = \mathbf{Q}(H|\Omega) = [\frac{2}{5}, \frac{3}{5}]$.
- Even though it is common knowledge that $\mathbf{Q}_1(H) = [\frac{1}{3}, \frac{2}{3}]$ and that $\mathbf{Q}_2(H) = [\frac{2}{5}, \frac{3}{5}]$!

Example of Agreeing to Disagree

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}.$$

- Instead of a precise prior, suppose the two agents begin with a common imprecise prior, an ϵ -contaminated class:
 $\mathbf{Q} = \{0.8p + 0.2q \mid q \in \Lambda\}$, where $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and Λ is the set of all distributions over \mathcal{A} .
- Suppose the true state is w_1 , at which
 $\mathbf{Q}_1(H) = \mathbf{Q}(H|\{w_1, w_2\}) = [\frac{1}{3}, \frac{2}{3}]$, whereas $\mathbf{Q}_2(H) = \mathbf{Q}(H|\Omega) = [\frac{2}{5}, \frac{3}{5}]$.
- Even though it is common knowledge that $\mathbf{Q}_1(H) = [\frac{1}{3}, \frac{2}{3}]$ and that $\mathbf{Q}_2(H) = [\frac{2}{5}, \frac{3}{5}]$!
- That is, the agents agree to disagree!

Dilation in the Example

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}$$

$\mathbf{Q} = \{0.8p + 0.2q \mid q \in \Lambda\}$, where $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and Λ is the set of all distributions over \mathcal{A} .

Dilation in the Example

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}$$

$\mathbf{Q} = \{0.8p + 0.2q \mid q \in \Lambda\}$, where $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and Λ is the set of all distributions over \mathcal{A} .

- Observe that H is *dilated* by \mathcal{P}^1 , in the sense that for every $E \in \mathcal{P}^1$, $[\underline{\mathbf{Q}}(H|E), \overline{\mathbf{Q}}(H|E)] = [\frac{1}{3}, \frac{2}{3}]$ strictly contains $[\underline{\mathbf{Q}}(H), \overline{\mathbf{Q}}(H)] = [\frac{2}{5}, \frac{3}{5}]$.

Dilation in the Example

$$\mathcal{P}^1$$

w_1	w_2
w_3	w_4

$$\mathcal{P}^1 = \{\{w_1, w_2\}, \{w_3, w_4\}\}; \mathcal{P}^2 = \{\Omega\}; H = \{w_1, w_4\}$$

$\mathbf{Q} = \{0.8p + 0.2q \mid q \in \Lambda\}$, where $p = (\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$, and Λ is the set of all distributions over \mathcal{A} .

- Observe that H is *dilated* by \mathcal{P}^1 , in the sense that for every $E \in \mathcal{P}^1$, $[\underline{\mathbf{Q}}(H|E), \overline{\mathbf{Q}}(H|E)] = [\frac{1}{3}, \frac{2}{3}]$ strictly contains $[\underline{\mathbf{Q}}(H), \overline{\mathbf{Q}}(H)] = [\frac{2}{5}, \frac{3}{5}]$.

Take-home Message

It is no accident that dilation occurs when the agents can agree to disagree!

Some Notations

- Suppose two agents have the same (imprecise) prior, \mathbf{Q} , over a measurable space (Ω, \mathcal{A}) .
- Agent i learns (privately) the value of a (measurable) partition of Ω , \mathcal{P}_i , and updates by full Bayesian conditioning.
- Assume that every member in the coarsest common refinement of \mathcal{P}^1 and \mathcal{P}^2 is non-null under every measure in \mathbf{Q} .
- Let w denote the true state of the world, and $\mathcal{P}^i(w)$ the member of \mathcal{P}^i that contains w . Agent i 's posterior of H is $\mathbf{Q}(H|\mathcal{P}^i(w))$.
- $\underline{\mathbf{Q}}(H|E) = \inf_{p \in \mathbf{Q}} p(H|E)$; $\overline{\mathbf{Q}}(H|E) = \sup_{p \in \mathbf{Q}} p(H|E)$.
- Let \mathcal{P} be the finest common coarsening of \mathcal{P}^1 and \mathcal{P}^2 . Let $\mathcal{C}_0 = \mathcal{P}(w)$, which is the finest event that is common knowledge.
- Let $\mathcal{P}_0^i = \{E \in \mathcal{P}^i \mid E \cap \mathcal{C}_0 \neq \emptyset\}$. Obviously \mathcal{P}_0^i is a partition of \mathcal{C}_0 .

Definition (Dilation)

\mathcal{P}_0^i is said to dilate H (with respect to \mathbf{Q}) if for every $E \in \mathcal{P}_0^i$, the closed interval $[\underline{\mathbf{Q}}(H|E), \overline{\mathbf{Q}}(H|E)]$ strictly contains $[\underline{\mathbf{Q}}(H|\mathcal{C}_0), \overline{\mathbf{Q}}(H|\mathcal{C}_0)]$.

Definition (Dilation)

\mathcal{P}_0^i is said to dilate H (with respect to \mathbf{Q}) if for every $E \in \mathcal{P}_0^i$, the closed interval $[\underline{\mathbf{Q}}(H|E), \overline{\mathbf{Q}}(H|E)]$ strictly contains $[\underline{\mathbf{Q}}(H|\mathcal{C}_0), \overline{\mathbf{Q}}(H|\mathcal{C}_0)]$.

Theorem (Agreement on lower and upper probabilities)

Suppose for both $i = 1, 2$, \mathcal{P}_0^i does not dilate H . If both $\mathbf{Q}(H|\mathcal{P}^1(w))$ and $\mathbf{Q}(H|\mathcal{P}^2(w))$ are common knowledge, then $\underline{\mathbf{Q}}(H|\mathcal{P}^1(w)) = \underline{\mathbf{Q}}(H|\mathcal{P}^2(w))$ and $\overline{\mathbf{Q}}(H|\mathcal{P}^1(w)) = \overline{\mathbf{Q}}(H|\mathcal{P}^2(w))$.

A Result on Full Agreement

Theorem (Full agreement)

Suppose \mathbf{Q} is closed and connected, and for both $i = 1, 2$, \mathcal{P}_0^i does not dilate H . If both $\mathbf{Q}(H|\mathcal{P}^1(w))$ and $\mathbf{Q}(H|\mathcal{P}^2(w))$ are common knowledge, then $\mathbf{Q}(H|\mathcal{P}^1(w)) = \mathbf{Q}(H|\mathcal{P}^2(w))$.

A Corollary for Density Ratio Priors

Definition (Density ratio class)

Let $\Omega = \{\omega_1, \dots, \omega_n\}$ and $\mathcal{A} = \mathbb{P}(\Omega)$. A density ratio class is defined by

$$\mathbf{D}_{\rho, k} = \{(q_1, \dots, q_n) \mid \sum q_j = 1 \text{ and } \frac{q_h}{q_j} \leq k \frac{\rho_h}{\rho_j}, \forall 1 \leq h, j \leq n\}$$

where $k \geq 1$ and (ρ_1, \dots, ρ_n) is a positive probability vector.

A Corollary for Density Ratio Priors

Definition (Density ratio class)

Let $\Omega = \{w_1, \dots, w_n\}$ and $\mathcal{A} = \mathbb{P}(\Omega)$. A density ratio class is defined by

$$\mathbf{D}_{\rho, k} = \{(q_1, \dots, q_n) \mid \sum q_j = 1 \text{ and } \frac{q_h}{q_j} \leq k \frac{\rho_h}{\rho_j}, \forall 1 \leq h, j \leq n\}$$

where $k \geq 1$ and (ρ_1, \dots, ρ_n) is a positive probability vector.

Corollary (Full agreement for density ratio priors)

Suppose \mathbf{Q} is a density ratio class. If both $\mathbf{Q}(H|\mathcal{P}^1(w))$ and $\mathbf{Q}(H|\mathcal{P}^2(w))$ are common knowledge, then $\mathbf{Q}(H|\mathcal{P}^1(w)) = \mathbf{Q}(H|\mathcal{P}^2(w))$.

- Suppose the agents are commonly known to be *dilation-averse*, who adopt $\mathbf{Q}(H|\mathcal{C}_0)$ instead of $\mathbf{Q}(H|\mathcal{P}^i(\mathbf{w}))$ as their posterior if \mathcal{P}_0^i dilates H , and otherwise update by Bayesian conditioning.

- Suppose the agents are commonly known to be *dilation-averse*, who adopt $\mathbf{Q}(H|\mathcal{C}_0)$ instead of $\mathbf{Q}(H|\mathcal{P}^i(\mathbf{w}))$ as their posterior if \mathcal{P}_0^i dilates H , and otherwise update by Bayesian conditioning.
- Then they cannot agree to disagree on the lower or upper posterior.

- Suppose the agents are commonly known to be *dilation-averse*, who adopt $\mathbf{Q}(H|\mathcal{C}_0)$ instead of $\mathbf{Q}(H|\mathcal{P}^i(\mathbf{w}))$ as their posterior if \mathcal{P}_0^i dilates H , and otherwise update by Bayesian conditioning.
- Then they cannot agree to disagree on the lower or upper posterior.
- If the (common) prior is closed and connected, they cannot agree not to fully agree.

Conclusion and Further Questions

- Given a common (imprecise) prior, the presence of dilation is necessary for agreeing to disagree on the lower or upper posterior.

Conclusion and Further Questions

- Given a common (imprecise) prior, the presence of dilation is necessary for agreeing to disagree on the lower or upper posterior.
- Under the usual topological assumptions, the presence of dilation is necessary for agreeing not to fully agree.

Conclusion and Further Questions

- Given a common (imprecise) prior, the presence of dilation is necessary for agreeing to disagree on the lower or upper posterior.
- Under the usual topological assumptions, the presence of dilation is necessary for agreeing not to fully agree.
- All the results can be generalized to Geanakoplos & Polemarchakis's communication setting.

Conclusion and Further Questions

- Given a common (imprecise) prior, the presence of dilation is necessary for agreeing to disagree on the lower or upper posterior.
- Under the usual topological assumptions, the presence of dilation is necessary for agreeing not to fully agree.
- All the results can be generalized to Geanakoplos & Polemarchakis's communication setting.
- What about agents whose priors agree only *partially*?

Conclusion and Further Questions

- Given a common (imprecise) prior, the presence of dilation is necessary for agreeing to disagree on the lower or upper posterior.
- Under the usual topological assumptions, the presence of dilation is necessary for agreeing not to fully agree.
- All the results can be generalized to Geanakoplos & Polemarchakis's communication setting.
- What about agents whose priors agree only *partially*?
- What about agents who update by other rules, e.g., the Dempster-Shafer rule?