# A Differential Approach to Causality in Staged Trees 

Christiane Görgen and Jim Q. Smith

PGM 2016

This research is funded by EPSRC grant EP/L505110/1.

## Causal manipulation on probability trees

- more general than interventions on DAGs
- easily done in symbolic framework ${ }^{1}$

[^0]
## Probability trees

## Probability trees

- event tree graphs



## Probability trees

- event tree graphs
- edge labels (probabilities)



## Staged probability trees

probability tree + conditional independence assumptions

## Staged probability trees

probability tree + conditional independence assumptions
highly useful in asymmetric problems

## Staged probability trees

probability tree + conditional independence assumptions
highly useful in asymmetric problems

- model selection techniques


## Staged probability trees

probability tree + conditional independence assumptions
highly useful in asymmetric problems

- model selection techniques
- propagation algorithms


## Staged probability trees

probability tree + conditional independence assumptions
highly useful in asymmetric problems

- model selection techniques
- propagation algorithms
- statistical equivalence classes


## Example

Students at Warwick university...

## Example

Students at Warwick university...


## Example

Students at Warwick university...


## Example

Students at Warwick university...


## Example

Students at Warwick university...


## Example

Students at Warwick university...


## Example

Students at Warwick university...


## Interventions (graphically)



[^1] Intelligence, 195:291-315, 2013.

## Interventions (graphically)

Impose policy forcing students to live in Coventry:


[^2] Intelligence, 195:291-315, 2013.

## Interventions (graphically)

Impose policy forcing students to live in Coventry:


[^3] Intelligence, 195:291-315, 2013.

## Interventions (graphically)

Impose policy forcing students to live in Coventry:

causal interventions ${ }^{2} \rightsquigarrow$ projections onto a subtree

[^4] Intelligence, 195:291-315, 2013.

## More flexible than DAGs

Staged trees contain discrete Bayesian networks as a special case

## More flexible than DAGs

Staged trees contain discrete Bayesian networks as a special case


## More flexible than DAGs

Staged trees contain discrete Bayesian networks as a special case


## More flexible than DAGs

Staged trees contain discrete Bayesian networks as a special case


## More flexible than DAGs

Staged trees contain discrete Bayesian networks as a special case

but are more general and more expressive!

Two questions

## Two questions

- What if we want to do causal manipulations in staged trees without referring to a graph?


## Two questions

- What if we want to do causal manipulations in staged trees without referring to a graph?
- What if there is a sequence of manipulations we want to perform consecutively?


## Replacing the graph by a polynomial



## Replacing the graph by a polynomial

Every staged tree is in one-to-one correspondence with a nested polynomial:


## Replacing the graph by a polynomial

Every staged tree is in one-to-one correspondence with a nested polynomial:

$c_{\mathcal{T}}(\boldsymbol{\theta})=\theta_{0}+\theta_{1} \theta_{3}+\theta_{1} \theta_{4}+\theta_{2} \theta_{3} \theta_{5} \theta_{7}+\theta_{2} \theta_{3} \theta_{5} \theta_{8}+\theta_{2} \theta_{3} \theta_{6}+\theta_{2} \theta_{4}$

## Replacing the graph by a polynomial

Every staged tree is in one-to-one correspondence with a nested polynomial:


## Interventions (symbolically)

Manipulate a tree using a differentiation operation on this polynomial:


## Interventions (symbolically)

Manipulate a tree using a differentiation operation on this polynomial:


$$
c_{\mathcal{T}}(\boldsymbol{\theta})=\theta_{0}+\theta_{1} \theta_{3}+\theta_{1} \theta_{4}+\theta_{2} \theta_{3} \theta_{5} \theta_{7}+\theta_{2} \theta_{3} \theta_{5} \theta_{8}+\theta_{2} \theta_{3} \theta_{6}+\theta_{2} \theta_{4}
$$

## Interventions (symbolically)

Manipulate a tree using a differentiation operation on this polynomial:


$$
c_{\mathcal{T}}(\boldsymbol{\theta})=\theta_{0}+\theta_{1} \theta_{3}+\theta_{1} \theta_{4}+\theta_{2} \theta_{3} \theta_{5} \theta_{7}+\theta_{2} \theta_{3} \theta_{5} \theta_{8}+\theta_{2} \theta_{3} \theta_{6}+\theta_{2} \theta_{4}
$$

$\frac{\partial}{\partial \theta_{2}} c_{\mathcal{T}}(\boldsymbol{\theta})=\theta_{3} \theta_{5} \theta_{7}+\theta_{3} \theta_{5} \theta_{8}+\theta_{3} \theta_{6}+\theta_{4}$

Advantages of the symbolic approach

## Advantages of the symbolic approach



## Advantages of the symbolic approach



Interventions on the polynomial are more general than vertex manipulations!

## Local differentiation operation

Replace a staged tree by a polynomial

$$
c_{\mathcal{T}}(\boldsymbol{\theta})=\sum_{\left(v_{0}, v_{1}\right) \in E\left(v_{0}\right)} \theta\left(v_{0}, v_{1}\right)\left(\sum_{\left(v_{1}, v_{2}\right) \in E\left(v_{1}\right)} \theta\left(v_{1}, v_{2}\right) \underset{\left(v_{k-1}, v_{k}\right) \in E\left(v_{k-1}\right)}{\left.\left(\cdots\left(\sum_{k} \theta\left(v_{k-1}, v_{k}\right)\right)\right)\right)}\right.
$$

## Local differentiation operation

Replace a staged tree by a polynomial

$$
c_{\mathcal{T}}(\boldsymbol{\theta})=\sum_{\left(v_{0}, v_{1}\right) \in E\left(v_{0}\right)} \theta\left(v_{0}, v_{1}\right)\left(\sum_{\left(v_{1}, v_{2}\right) \in E\left(v_{1}\right)} \theta\left(v_{1}, v_{2}\right) \underset{\left(v_{k-1}, v_{k}\right) \in E\left(v_{k-1}\right)}{\left.\left(\cdots\left(\sum_{k} \theta\left(v_{k-1}, v_{k}\right)\right)\right)\right)}\right.
$$

and perform a local differentiation on that:

$$
\sum_{\left(v_{0}, v_{1}\right) \in E\left(v_{0}\right)} \theta\left(v_{0}, v_{1}\right)\left(\cdots \left(\frac{\partial}{\partial \theta_{j}^{\star}} \sum_{\left(v_{j}-v_{j}\right) \in E\left(v_{j}\right)} \theta\left(v_{j-1}, v_{j}\right) \underset{\left(v_{k-1}, v_{k}\right) \in E\left(v_{k-1}\right)}{\left.\left(\cdots\left(\sum_{k} \theta\left(v_{k-1}, v_{k}\right)\right)\right)\right)}\right.\right.
$$

## Example: two interventions



## Example: two interventions

Differentiate locally on florets:


## Example: two interventions

Differentiate locally on florets:


## Advantages of this new differentiation

- can do sequence of interventions


## Advantages of this new differentiation

- can do sequence of interventions
- does not rely on graphical representation $\rightsquigarrow$ flexible and very general


## Advantages of this new differentiation

- can do sequence of interventions
- does not rely on graphical representation $\rightsquigarrow$ flexible and very general
- used only algebraic description of a parametric model: method can be used in models far more general than staged trees


## Thank you very much for your attention!

## A Differential Approach to Causality in Staged Trees

Christiane Görgen<br>C.GORGEN@ WARWICK.AC.UK<br>Jim Q. Smith<br>J.Q.SMITH@WARWICK.AC.UK<br>Department of Statistics<br>University of Warwick<br>Coventry CV4 7AL, United Kingdom


#### Abstract

In this paper, we apply a recently developed differential approach to inference in staged tree models to causal inference. Staged trees generalise modelling techniques established for Bayesian networks (BN). They have the advantage that they can depict highly nuanced structure impossible to express in a BN and also enable us to perform causal manipulations associated with very general types of interventions on the system. Conveniently, what we call the interpolating polynomial of


[^0]:    ${ }^{1}$ Adnan Darwiche. A differential approach to inference in Bayesian networks. J. ACM, 50(3):280-305 (electronic), 2003.

[^1]:    ${ }^{2}$ Peter Thwaites. Causal Identifiability via Chain Event Graphs. Artificial

[^2]:    ${ }^{2}$ Peter Thwaites. Causal Identifiability via Chain Event Graphs. Artificial

[^3]:    ${ }^{2}$ Peter Thwaites. Causal Identifiability via Chain Event Graphs. Artificial

[^4]:    ${ }^{2}$ Peter Thwaites. Causal Identifiability via Chain Event Graphs. Artificial

