

Imprecise Swing Weighting for Multi-Attribute Utility Elicitation Based on Partial Preferences

Matthias C. M. Troffaes¹ Ullrika Sahlin²



¹Durham University, United Kingdom

²Lund University, Sweden

10 July, 2017

The Crab of Imprecision





The Crab of Imprecision

Imprecise Probability



The Crab of Imprecision

Imprecise Probability

Imprecise Utility



The Crab of Imprecision

Imprecise Probability

Imprecise Utility

Elicitation & Inference

Outline

Assumptions

Main Contributions & Results

Application

Conclusion

- Main Messages

- Further Reading

The background of the slide is a dense field of colorful, semi-transparent spheres, each with a different number printed on it. The colors include shades of green, yellow, pink, light blue, and white. The numbers are in various orientations and sizes, creating a busy, textured effect.

Outline

Assumptions

Main Contributions & Results

Application

Conclusion

Main Messages

Further Reading

Assumptions

Rewards

Each reward $r = (a_1, \dots, a_n)$ comprises of n attributes. Set of rewards $\mathcal{R} := \mathcal{A}_1 \times \dots \times \mathcal{A}_n$.

Lotteries

A lottery ℓ on \mathcal{R} = probability mass function over \mathcal{R} . $L(\mathcal{R})$ = set of all lotteries over \mathcal{R} .

Utility Function

... on \mathcal{R} = any function $U: \mathcal{R} \rightarrow \mathbb{R}$. Lifted to $L(\mathcal{R})$ in the usual way: $U(\ell) := \sum_{r \in \mathcal{R}} \ell(r)U(r)$

Preferences

We assume that our preferences form a preorder \succeq on $L(\mathcal{R})$ and can be represented through a set \mathcal{U} of utility functions $U: L(\mathcal{R}) \rightarrow \mathbb{R}$:

$$\ell_1 \succeq \ell_2 \iff \forall U \in \mathcal{U}: U(\ell_1) \geq U(\ell_2)$$

Procedure for identifying \mathcal{U} ?

Assumptions

Additive Form

$$U(a_1, \dots, a_n) = \sum_{i=1}^n k_i U_i(a_i)$$

Marginal Utility Functions

U_1, \dots, U_n assumed to be known precisely.

Attribute Weights

k_1, \dots, k_n not assumed to be known.

Procedure for identifying a set of attribute weights?

Outline

$\frac{pc}{E} = \frac{m_0 c^2}{m c^2} = \beta$, $\Delta x \Delta p_x \geq \hbar$, $\Delta y \Delta p_y \geq \hbar$, $\Delta z \Delta p_z \geq \hbar$, $\Delta p_x = p \sin \varphi = \frac{h}{\lambda} \sin \varphi$, $\Delta x \sin \varphi = \lambda$, $\Delta x \Delta p_x = h$, $\Delta x \Delta v_x \geq h/m$, $\Delta x = \frac{h}{m \Delta v_x}$, $\Delta E \Delta t \geq \hbar$



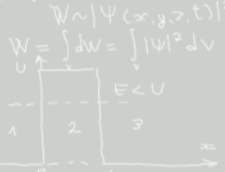
Assumptions

$2m = p_x^2 / (2m)$, $|\Psi|^2 = \Psi \Psi^* = |A|^2$, $U(x) = \begin{cases} \infty, & x < 0 \\ 0, & 0 \leq x < l \\ \infty, & x > l \end{cases}$
 $E = \frac{n^2 \pi^2 \hbar^2}{2m l^2}$ ($n=1, 2, 3, \dots$)



Main Contributions & Results

$\Delta E_n = E_{n+1} - E_n = \frac{\pi^2 \hbar^2}{2m l^2} (2n+1) \approx \frac{\pi^2 \hbar^2}{m l^2} n$
 $\beta = \sqrt{2m(U-E)}/\hbar$, $D = |A_3|^2 / |A_1|^2$
 $\frac{1}{D} = 2d \omega \sum_n \int \int \frac{(\beta_{n,n'}^2 \sin^2 \alpha)^2}{(x^2 + z^2)} \delta(z^2 + 2z k + b_{n,n'}) \psi_1(x)$



$W \sim |\Psi(x,y,z,t)|^2$
 $\int_{-\infty}^{\infty} |\Psi|^2 dV = \int_{-\infty}^{\infty} |W|^2 dV = 1$
 $\Psi = \sum_n c_n \Psi_n$

Application

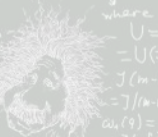
$\alpha = \sqrt{\frac{m}{2\hbar \omega}} \frac{q^2}{\kappa} \left(\frac{1}{\epsilon_\infty} - \frac{1}{\epsilon_0} \right)$, $r_p = \sqrt{\frac{\hbar}{2m\omega}}$; $\epsilon_{\infty} \alpha \omega = \sum_n \frac{\beta^2 (x^2 - b_{n,n'})}{\sqrt{x^2 + z^2}} [J_{n,n'}(a(z,l)) K_{n,n'} + J_{n,n'}'(a(z,l)) K_{n,n'}'(a(z,l))] e^{-S_0}$



$\begin{cases} \Psi_1(0) = \Psi_2(0) \\ \Psi_1'(0) = \Psi_2'(0) \\ \Psi_2(l) = \Psi_3(l) \\ \Psi_2'(l) = \Psi_3'(l) \end{cases}$

Conclusion

$H = -k_y S^2 (\sin^2 \theta \sin^2 \phi - 1) + k_z S^2 \cos^2 \theta$, $e^{-S_0} = 2 \cos(\pi S) e^{-S_0}$
 $J(\omega) = \frac{\omega}{2\delta c} \theta(\omega - 2c/\delta) \sqrt{\omega^2 - (2c/\delta)^2}$, $\sum_n e^{-k_n d} Z_n = N \exp\{-\beta E(k,c)\}$
 $E(k) = \frac{\Delta}{4} |\sin kd|$
 $D = D_0 \exp\left(-\frac{2}{\hbar} \sqrt{2m(U-E)} l\right)$



$\frac{1}{2} [(2\phi_0)^2 + c^2 (\gamma_c \phi_0)^2 + (m_{00}^2 + (q - q_0)^2) \phi_0^2] + \frac{U_0}{4!} (\phi_0^4)^2$, $\chi(k, \omega_n) = \int dt \int dx (\delta^2(x, it) \delta^2(t, 0)) D = D_0 \exp\left[-\frac{\beta}{\hbar} \sqrt{2m(U-E)} dx\right]$
 $H_3 = \sum_{(i,j)} H(i,j)$, $H(i,j) = \sum_{\mu} J_{\mu}(i,j) S_{\mu}(i) S_{\mu}(j)$, $H^{(2)}(i,j) = -2(\gamma_0^2 |T_{ij}| \frac{1}{4} T_{ij} / \Psi_0)$
 $E = -A \sum_n \sin(\theta_n + \theta_{n+1}) - B \sum_n \cos 2\theta_n$
 $S(t) = \sum_{\alpha} s^2 N_{\alpha}(t) / \sum_{\alpha} N_{\alpha}(t)$
 $M = -\partial E / \partial H = [X_{ij} + 2\tilde{y} \sin^2(\theta - \alpha)] H - M_0 [\cos(\theta + \alpha) + y \sin 2\theta \sin(\theta - \alpha)]$
 $\frac{d^2 \delta}{dQ d\omega} \approx \sum_{\alpha\beta} |f(Q)|^2 \left(1 - \frac{Q_{\alpha} Q_{\beta}}{Q^2} \right) S^{\alpha\beta}(Q, \omega)$, $H = J \sum (S_i^x S_{i+1}^x + E (S_i^x S_{i+1}^y + S_i^y S_{i+1}^x))$, $\omega_{ac}(q) = J [J_1 - \omega_{\beta}(q) = J/2 + e^J \cos(2qa) - J_2 \cos(2qa)]$
 $S^{\alpha\beta}(Q, \omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \langle S^{\alpha}(Q, 0) S^{\beta}(Q, t) \rangle \exp(i\omega t) dt$, $\omega_{\pm}(Q) = J(1 \pm 2E \cos(Qa))$, $\omega_{\pm}(Q) = \pi/a \pm J \sin(Qa)$
 $S^{\alpha}(Q, 0) = \sum_i S_i^{\alpha} \exp(iQ \cdot R_i)$, $H = -\frac{3}{4J} + J \sum [a_{\alpha}^{\dagger}(i) a_{\alpha}(i) + a_0^{\dagger}(i) a_0(i) + a_{\alpha}^{\dagger}(i) a_0(i) + a_0^{\dagger}(i) a_{\alpha}(i)]$

Contribution 1: General Method for Eliciting Bounds on Weights

Elicitation

- (i) Consider *any* joint rewards r_0, \dots, r_n for which we have that $r_0 \leq r_j \leq r_n$
- (ii) Find largest $\underline{\alpha}_j$ and smallest $\bar{\alpha}_j$ so that $(1 - \underline{\alpha}_j)r_0 \oplus \underline{\alpha}_j r_n \leq r_j \leq (1 - \bar{\alpha}_j)r_0 \oplus \bar{\alpha}_j r_n$

1. Generalises classical swing weighting
2. Generalises various imprecise methods from literature (Mustajoki 2005, Riabacke 2009, Gomes 2011, ...)
3. Clean operational interpretation which is not stated in literature (as far as I know)

Contribution 2: Linear Constraint Representation

Notation

With $r_j = (a_{j1}, \dots, a_{jn})$, let $u_j := (U_1(a_{j1}), \dots, U_n(a_{jn}))$. Let $k := (k_1, \dots, k_n)$.

Inference Theorem

Stated preferences lead to a set of linear inequalities on weights (k_1, \dots, k_n) :

$$\forall j \in \{1, \dots, n-1\}: (u_j - (1 - \underline{\alpha}_j)u_0 - \underline{\alpha}_j u_n) \cdot k \geq 0 \geq (u_j - (1 - \bar{\alpha}_j)u_0 - \bar{\alpha}_j u_n) \cdot k$$
$$1 \cdot k = 1$$

Contribution 3: Consistency and Uniqueness

What is Consistency & Uniqueness?

1. Existence of a solution for all possible choices of $0 \leq \underline{\alpha}_j \leq \bar{\alpha}_j \leq 1$
2. Uniqueness of solution when $\underline{\alpha}_j = \bar{\alpha}_j$ for all j

Uniqueness Theorem

Assume that u_0 is constant, and that the vectors $(u_1, \dots, u_{n-1}, 1)$ are linearly independent. Let λ_j be the coefficients that decompose u_n as a linear combination of $(u_1, \dots, u_{n-1}, 1)$:

$$u_n = \lambda_n + \sum_{j=1}^{n-1} \lambda_j u_j$$

Then the precise case has a unique solution if and only if $\sum_{j=1}^{n-1} \alpha_j \lambda_j \neq 1$.

Consistency Theorem

When $\lambda_1 \leq 0, \dots, \lambda_{n-1} \leq 0$, then solution exists for all possible choices of $0 \leq \underline{\alpha}_j \leq \bar{\alpha}_j \leq 1$.

Outline

Assumptions

Main Contributions & Results

Application

Conclusion

Main Messages

Further Reading



Application: Marmorkrebs

What is Marmorkrebs?

Origin unknown, first known individuals from pet trade 1990's.
Can reproduce asexually, high reproduction rate, damages ecosystems.

Ecological Decision Problem

Eradicate invasive marmorkrebs recently observed in a lake

Options

- (I) Do nothing
- (II) Mechanical removal
- (III) Drain system and remove individuals by hand
- (IV) Drain system, dredge and sieve to remove individuals
- (V) Decomposable biocide plus drainage
- (VI) Increase pH plus drainage and removal by hand

Application: Marmorkrebs

Approach

1. Identify attributes
2. Elicit marginal utility of each attribute under each option & outcome
3. Identify rewards r_0, \dots, r_n that are easy to interpret by experts
4. Elicit α bounds
5. Elicit probability bounds on each outcome under each decision
act-state dependence! very common in ecological decision making
6. Solve quadratic linear programming problem for inference with interval dominance

more details on poster & in paper

Outline

Assumptions

Main Contributions & Results

Application

Conclusion

Main Messages
Further Reading



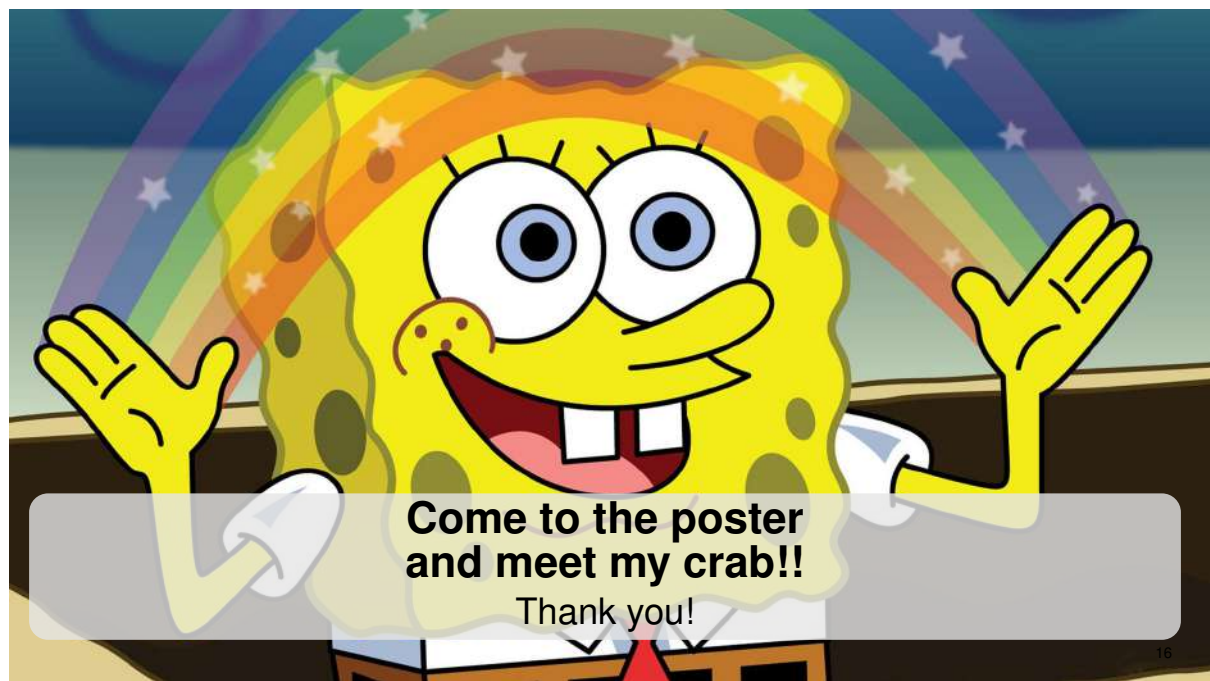
Conclusion: Main Messages

Extremely Flexible Generalisation of Swing Weighting

- (i) Operational
- (ii) Partial preferences when attributes are hard to weigh
- (iii) Flexible choice of rewards to match expert experience
- (iv) Strong consistency & uniqueness properties

Demonstrated Benefits of Imprecision in Ecological Decision Making

- (i) Value ambiguity expressed through direct comparison of simple lotteries
- (ii) Uncertainty about success more reliably incorporated with intervals
- (iii) Realm of quadratic programming
- (iv) Act-state dependence means interval dominance
- (v) High imprecision in inputs does not need to imply vacuous results

A vibrant illustration of SpongeBob SquarePants. He is yellow with large, expressive blue eyes and a wide, open-mouthed smile showing his two front teeth. He has his hands raised in a friendly gesture. The background features a multi-colored rainbow arching over him, with several white stars scattered across the sky. The overall scene is bright and cheerful.

**Come to the poster
and meet my crab!!**

Thank you!

References I

- [1] F. J. Anscombe and R. J. Aumann.
A definition of subjective probability.
Annals of Mathematical Statistics, 34(1):199–205, March 1963.
- [2] P. Bohman and L. Edsman.
Marmorkräftan i Märstaån. Riskanalys och åtgärdsförslag.
Aqua Reports 2013:17, Sveriges lantbruksuniversitet, Drottningholm, 2013.
- [3] Mats Danielson, Love Ekenberg, Aron Larsson, and Mona Riabacke.
Weighting under ambiguous preferences and imprecise differences in a cardinal rank ordering process.
International Journal of Computational Intelligence Systems, 7:105–112, 2014.
doi:10.1080/18756891.2014.853954.
- [4] Luiz Flávio Autran Monteiro Gomes, Luis Alberto Duncan Rangel, and Miguel da Rocha Leal Junior.
Treatment of uncertainty through the interval smart/swing weighting method: a case study.
Pesquisa Operacional, 31(3):467–485, 12 2011.
doi:10.1590/S0101-74382011000300004.
- [5] Ralph L. Keeney and Howard Raiffa.
Decisions with Multiple Objectives: Preferences and Value Tradeoffs.
Cambridge University Press, 1993.

References II

- [6] Jyri Mustajoki, Raimo P. Hämäläinen, and Ahti Salo.
Decision support by interval SMART/SWING: Incorporating imprecision in the SMART and SWING methods.
Decision Sciences, 36(2):317–339, 2005.
doi:10.1111/j.1540-5414.2005.00075.x.
- [7] Mona Riabacke, Mats Danielson, and Love Ekenberg.
State-of-the-art prescriptive criteria weight elicitation.
Advances in Decision Sciences, 2012.
doi:10.1155/2012/276584.
- [8] Mona Riabacke, Mats Danielson, Love Ekenberg, and Aron Larsson.
A Prescriptive Approach for Eliciting Imprecise Weight Statements in an MCDA Process, pages 168–179.
Springer Berlin Heidelberg, 2009.
doi:10.1007/978-3-642-04428-1_15.
- [9] Teddy Seidenfeld, Mark J. Schervish, and Jay B. Kadane.
A representation of partially ordered preferences.
The Annals of Statistics, 23:2168–2217, 1995.
- [10] Detlof von Winterfeldt and Ward Edwards.
Decision Analysis and Behavioral Research.
Cambridge University Press, Cambridge, 1986.